

Page	Changes to make																
15	Table 2.3: 20.96 – 21.82 interval, change 3/60 to 3/50																
44	Example 3.1: $\bar{D} = \frac{\sum D_i}{n} = \frac{3183.44}{15} = 212.223$																
75	Table at top of page, two-tailed test rejection region: $ t  > t_{\alpha/2}$																
84	Problem 5.12, 3 <sup>rd</sup> line: variance																
115	Remove $D$ from Equation (7.23) to read $\varepsilon = f_d \mu \tan v$																
125	Line 4 with “In this example...” change (10/1,000,000) to (3/1,000,000) = ±0.0014 ft																
125	Equation $\sigma = \sqrt{(0.003)^2 + (0.01)^2 + (0.0098)^2 + (0.0014)^2} = \pm 0.020$ ft																
125	$E_{95} = 1.96\sigma = \pm 0.028$ ft																
128	<table border="0"> <tr> <td>Problem 7.17</td> <td>AB</td> <td>321.31</td> </tr> <tr> <td>Change Course</td> <td>BC</td> <td>276.57</td> </tr> <tr> <td>column as follows:</td> <td>CD</td> <td>100.30</td> </tr> <tr> <td></td> <td>DE</td> <td>306.83</td> </tr> <tr> <td></td> <td>EA</td> <td>255.48</td> </tr> </table>	Problem 7.17	AB	321.31	Change Course	BC	276.57	column as follows:	CD	100.30		DE	306.83		EA	255.48	
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137	Equation (8.11) missing 1 zero, 0, in last row under $\sigma_{EA}^2$																
161	Example 9.6, solution: “From Equation (7.38) and converting 5 mm to 0.0164 ft, the ...																
175	Table 10.3: $v^2$ and $wv^2$ should be $v^2$ and $wv^2$																
206	Problem 11.14: Change angle 2 value to 69°02'34”																
223	Problem 12.1: Change line 3 difference in elevation to -2.02																
260	Problem 14.6: Change reference to Figure 14.4																
282	Element (2,1) in inverse matrix should be negative, as -0.00200050																
286	<p>Inverse Matrix should be:</p> <table border="0"> <tr> <td>0.00700</td> <td>-0.00497</td> <td>0.00160</td> <td>-0.01082</td> </tr> <tr> <td>-0.00497</td> <td>0.00762</td> <td>0.00148</td> <td>0.01138</td> </tr> <tr> <td>0.00160</td> <td>0.00148</td> <td>0.00378</td> <td>0.00073</td> </tr> <tr> <td>-0.01082</td> <td>0.01138</td> <td>0.00073</td> <td>0.02365</td> </tr> </table>	0.00700	-0.00497	0.00160	-0.01082	-0.00497	0.00762	0.00148	0.01138	0.00160	0.00148	0.00378	0.00073	-0.01082	0.01138	0.00073	0.02365
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291	Problem 15.8: Change last angle observation to B D C 26°23'37”																
310	Remove 19 <sup>th</sup> row and column from $W$ matrix and also row 20 from $K$ matrix																
318	Change coordinate values in Problem 16.3 to:																
	<table border="1"> <thead> <tr> <th>Station</th> <th>X (ft)</th> <th>Y (ft)</th> </tr> </thead> <tbody> <tr> <td>A</td> <td>10,697.62</td> <td>8727.73</td> </tr> <tr> <td>B</td> <td>10,968.62</td> <td>11,204.40</td> </tr> <tr> <td>C</td> <td>13,166.76</td> <td>11,226.99</td> </tr> <tr> <td>D</td> <td>13,618.44</td> <td>8870.76</td> </tr> </tbody> </table>	Station	X (ft)	Y (ft)	A	10,697.62	8727.73	B	10,968.62	11,204.40	C	13,166.76	11,226.99	D	13,618.44	8870.76	
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357	Problem 17.7: Control coordinates are all incorrect. Should be																
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357	Change $\Delta Y$ to -14,266.417																
361	Change baseline CE: to baseline EC:																
363	Change control station coordinates as follows																

Station	X(m)	Y(m)	Z(m)
A	1,659,858.133	4,412,163.817	4,282,198.830
C	1,659,393.372	4,411,659.134	4,282,897.823

476 Change equation (22.28) to

$$F: S[r_{11}(x + v_x) + r_{21}(y + v_y) + r_{31}(z + v_z)] + Tx - (X + V_X) = 0$$

$$G: S[r_{12}(x + v_x) + r_{22}(y + v_y) + r_{32}(z + v_z)] + Ty - (Y + V_Y) = 0$$

$$H: S[r_{13}(x + v_x) + r_{23}(y + v_y) + r_{33}(z + v_z)] + Tz - (Z + V_Z) = 0$$

476 Change Equation (22.29) to

$$\begin{bmatrix} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial y} & \frac{\partial F}{\partial z} & \frac{\partial F}{\partial X} & 0 & 0 \\ \frac{\partial G}{\partial x} & \frac{\partial G}{\partial y} & \frac{\partial G}{\partial z} & 0 & \frac{\partial G}{\partial Y} & 0 \\ \frac{\partial H}{\partial x} & \frac{\partial H}{\partial y} & \frac{\partial H}{\partial z} & 0 & 0 & \frac{\partial H}{\partial Z} \end{bmatrix} \begin{bmatrix} v_x \\ v_y \\ v_z \\ v_X \\ v_Y \\ v_Z \end{bmatrix}$$

where

$$\begin{array}{llll} \frac{\partial F}{\partial x} = Sr_{11} & \frac{\partial F}{\partial y} = Sr_{21} & \frac{\partial F}{\partial z} = Sr_{31} & \frac{\partial F}{\partial X} = -1 \\ \frac{\partial G}{\partial x} = Sr_{12} & \frac{\partial G}{\partial y} = Sr_{22} & \frac{\partial G}{\partial z} = Sr_{32} & \frac{\partial G}{\partial Y} = -1 \\ \frac{\partial H}{\partial x} = Sr_{13} & \frac{\partial H}{\partial y} = Sr_{23} & \frac{\partial H}{\partial z} = Sr_{33} & \frac{\partial H}{\partial Z} = -1 \end{array}$$

517 Last line on page, change "...with 25 unknowns..." to "...with 19 unknowns..."

523 Local coordinates should be

Local Coordinates			
Station	E (ft)	N (ft)	h (ft)
1	7405.583	6812.877	248.31
5	6641.129	7734.808	221.29
22	9342.342	7375.175	249.81
102	11,341.155	7944.178	312.56

Units for satellite ellipsoid height are listed in feet. In meters they are as shown below.

Satellite Coordinates			
Station	X (m)	Y (m)	h (m)
1	-335.415	-280.544	40.3742
5	-624.878	-58.153	31.9864
22	202.292	17.357	40.7997
102	757.950	321.418	59.9799